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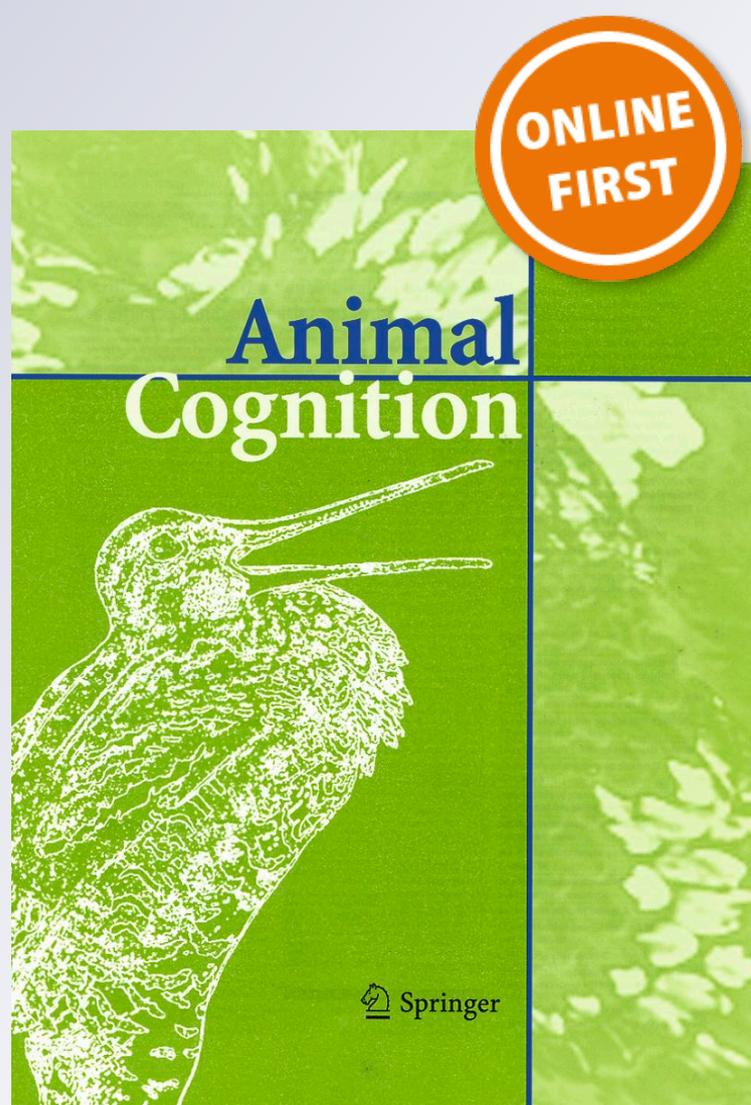
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A study of sharing and reciprocity in grey parrots (*Psittacus erithacus*)

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Abstract Demonstrations of nonhuman ability to share resources and reciprocate such sharing seem contingent upon the experimental paradigm used (note Horner et al. in PNAS 108:13847–13851, 2011). Here, such behaviour in Grey parrots (*Psittacus erithacus*) was tested in two experiments, both designed to avoid possible issues involving apparatus complexity, visible reward options, and physical competition and/or limited communication between subjects. In both studies, two birds, working in dyads, took turns in choosing one of four different coloured cups with differing outcomes: empty (null, nonrewarding), selfish (keeping reward for oneself), share (sharing a divisible reward), or giving (donating reward to other). In Experiment 1, each bird alternated choices with a conspecific; in Experiment 2, each bird alternated with the three humans with different specific intentions (selfish, giving, or copying bird's behaviour). In both experiments,

birds could learn to cooperatively reward a partner at little cost to themselves—by sharing—and potentially maximize overall reward by reciprocating such sharing. Experiment 1 results differed depending upon which bird began a session: Only our dominant bird, as follower, was willing to share. In Experiment 2, birds' responses tended towards consistency with human behaviour. Our dominant bird was willing to share a reward with a human who was willing to give up her reward, was selfish with the selfish human, and tended towards sharing with the copycat human; our subordinate bird tended slightly towards increased sharing with the generous human and selfishness with the selfish human, but did not change behaviour with the copycat.

Keywords *Psittacus erithacus* · Parrot · Value attribution · Nonhuman sharing · Reciprocity · Mutualism

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Introduction

Much scientific study currently centres on sharing, reciprocity, and prosociality—determining whether subjects behave so as to benefit another individual, usually at little personal cost, and if such behaviour is contingent upon similar behaviour in a partner (e.g. Dawkins 2010; Rustagi et al. 2010). Children are often tested to see how and when such behaviour develops and what behavioural elements and social conditions must be in place for it to be exhibited (e.g. Warneken et al. 2011; see Kärtner et al. 2010). By studying group-living nonhuman primates, however, researchers also aim to uncover what evolutionary pressures may have selected for such behaviour: whether the selection process depends on culture, genes, a combination thereof—or simply requires social living (see Bell et al.

2009; Hamilton 1975; Simpson and Beckes 2009). From an evolutionary standpoint, researchers (see Jolly 1966; Humphrey 1976) have long argued that primate intelligence was a correlate of complicated social and ecological systems and long lives; that is, an outcome of selection processes favouring animals that flexibly transfer skills across domains and remember and act upon knowledge of detailed intragroup social relations. The expectation was that long-lived primates in coherent social groups—humans and closely related apes—would likely demonstrate prosociality, sharing or reciprocity: They might demonstrate an understanding of the underlying concepts by maximizing possible payoff during a task by remembering and repaying positive actions of those within their social group or at least attend to one other's behaviour—even if selfish or neutral—in order to reciprocate in kind.

Such behaviour in nonprimates has, in contrast, received relatively little attention and then mostly in corvids (e.g. DiLascio et al. 2012; Scheid et al. 2008; Schwab et al. 2012; Seed et al. 2008; von Bayern et al. 2007). Notably, data on avian species might provide evidence for convergent evolution of such traits, whereas lack thereof might assist in determining what ethological, ecological, and possibly even neurological constraints might be preconditions for their existence. Given many parallels between primates and some corvids and psittacids—complex social lives, highly developed cognitive and communicative abilities (e.g. referential vocal behaviour, cooperation and reconciliation, possible deception and coalition formation) that suggest convergent evolution (Bugnyar 2007; Clayton and Emery 2005; Emery 2004; Emery et al. 2007; Fraser and Bugnyar 2010a, b, 2011; Pepperberg 1999, 2010; Seed et al. 2008), parrots might also be good subjects for studies involving some level of prosocial behaviour. Specifically, long-term studies on Grey parrots show they learn best in social contexts (Pepperberg 1999; Pepperberg et al. 1998, 1999, 2000), that their cognitive competence is often comparable to that of young children (Pepperberg 1999, 2006a, b; Pepperberg and Gordon 2005; Pepperberg and Carey 2012), and that although Grey parrots do not, like some other psittacids, engage in cooperative breeding and nest sharing, in the wild they are highly social, live in large flocks (May 2004), display altruistic behaviours (e.g. regurgitation, mutual interaction such as grooming), and cooperate by mobbing in the presence of a predator (Jones and Tye 2006). Recent studies suggest some ability to cooperate with one another (Péron et al. 2011a) and to adapt responses according to experimenters' behavioural cues (Giret et al. 2009; Péron et al. 2010, 2011b).

Interestingly, a review of current literature suggests that the presence or absence of prosocial behaviour, sharing, or reciprocity appears dependent not only upon the species tested but also upon parameters of the task used: whether the task

involves solicitation of food (and whether food is visible) or solicitation of assistance, the need to coordinate behaviour either in concert or sequentially, whether subjects must perform the same tasks or somewhat different tasks hierarchically, and whether dominance rank is taken into account (see Horner et al. 2011 for a review; note also Henderson and Woodward 2011). We begin by discussing some of these issues according to species; the purpose of this discussion is to provide justification for the techniques we chose to employ.

Studies on great apes (primarily chimpanzees), the evolutionarily closest primates to humans, corroborate effects of experimental design on results. Directly observable food rewards seemed to inhibit prosociality (Bullinger et al. 2011; Jensen et al. 2006; Silk et al. 2005; Vonk et al. 2008). The few studies examining reciprocity (e.g. Brosnan et al. 2009; de Waal 1997; Melis et al. 2008, 2009; Yamamoto and Tanaka 2009; Yamamoto et al. 2009) found weak effects of partners' previous behaviour, primarily with grooming-food exchanges. If assistance rather than food sharing was studied, chimpanzees showed some cooperation (Warneken et al. 2007). Results also appeared contingent upon whether tasks involved simultaneous reward versus cooperation to enable a partner to receive reward subsequently (Greenberg et al. 2010; note Melis et al. 2009; Yamamoto et al. 2009). Dominance hierarchies may play a role (Melis et al. 2009), and whether partners actively solicit assistance (Yamamoto et al. 2009, but see Melis et al. 2011). Using token exchange rather than reciprocal actions, orangutans but not chimpanzees, bonobos, or gorillas cooperated with conspecifics (Brosnan and Beran 2009; Bullinger et al. 2011; Dufour et al. 2009; Pelé et al. 2009). When tokens were chosen, not exchanged, chimpanzees did demonstrate some prosociality (Horner et al. 2011).

Monkey studies also vary in aims, design, and results. Neither capuchins nor Tonkean macaques engaged in conspecific token exchanges (Pelé et al. 2010) but capuchins showed limited cooperative, reciprocal altruism for direct food reward and prosociality when (a) it was pitted against selfishness, (b) partners were familiar and visible, and (c) subjects chose tokens that were immediately traded for reward (Brosnan et al. 2006; de Waal et al. 2008; Hattori et al. 2005; Lakshminarayanan and Santos 2008; Takimoto et al. 2010). Dominance influenced results for long-tailed macaques (Massen et al. 2010, 2011): higher ranked individuals shared more; lowest ranked ones were more selfish. Such behaviour might have occurred because here subordinates could be selfish without immediate (e.g. aggressive) reprisal and dominants could share at no personal cost, but the results also suggest that dominants may use prosociality to emphasize their rank (see de Waal 1989; Zahavi 2004).

Cooperatively breeding monkeys (e.g. Callithrichids) have also been studied—species in which stronger and

more human-like social interactions (Hrdy 2009) might promote prosociality (Burkart et al. 2007) despite further evolutionary distance from humans. Again, results depended upon experimental conditions and aims: Common marmosets (*Callithrix jacchus*) but not cottontop tamarins (*Saguinus oedipus*) chose to cooperate compared to a control in which food was delivered to an empty cage (Burkart et al. 2007; Cronin et al. 2009; Stevens 2010). Cottontops, however, were prosocial when the task used immediate equal rewards (Cronin and Snowdon 2008); and, in a later study, prosociality was not initially strong but emerged over time (Cronin et al. 2010).

Given our awareness of these many issues that could affect the experimental outcome—e.g. apparatus complexity, visible reward options, physical competition and/or limited communication between subjects—we designed a protocol to avoid as many of them as possible. And, as a first step, we chose to examine behaviour related to, but not isomorphic with, prosociality: Would our birds share rewards if the payoff for sharing and being selfish were the same, and, given the turn-taking nature of the task we designed, would they reciprocate—or learn to reciprocate—to maximize payoff over time?

Because responding can be affected strongly by the sight or absence of food rewards (e.g. Warneken et al. 2007; also Boysen et al. 1996), we used a token system: Birds could choose one of four presented cups, leading to (a) no reward (null/spiteful, sensu Hamilton 1964), (b) reward for oneself (selfish), (c) reward for the other individual (giving), or (d) equal reward for both (sharing). (We use “giving” to emphasize the action without imputing intent.) Our parrots had a long history of understanding relationships between use of human vocal labels and various outcomes (Pepperberg 1999; Pepperberg and Wilkes 2004) and in manipulating small objects such as the cups for reward (e.g. Pepperberg et al. 1997); thus we did not expect any difficulty in their learning the value of each individual cup colour.

Despite involving multiple conditions/outcomes, this protocol had advantages of simplicity of use—birds did not need to learn to manipulate a novel apparatus, coordinate physical actions, or overtly communicate with each other, although results of each others' actions were immediately made visible by the human experimenter. Notably, the system also avoided simultaneous competition for overt rewards, as only one bird could choose at a time, and prevented the birds, who were, outside of sessions, housed in or on separate cages within a large room, from engaging in physical retribution. (NB: They interact aggressively if in close proximity in the absence of humans.) We studied the four conditions simultaneously in order to better model real-life conditions, rather than constraining birds to a limited number of artificial, human-designated choices that might not reflect behaviour in the wild.

Dyadic responding may be affected by the relationship between the subjects involved (e.g. de Waal et al. 2008; Massen et al. 2010, 2011; Melis et al. 2009); we thus performed two experiments to address this issue. The first involved a parrot–parrot dyad in which one bird was known to be dominant. Here we alternated birds' positions as leader and follower to see whether their behaviour would be affected if the dominant bird had to follow and the subordinate bird was given the chance to lead. The second experiment associated each parrot with humans who, with respect to each bird, would consistently be selfish, giving, or copy the parrot's action (“copycat”), and with whom dominance issues should not exist. To ensure that birds did not learn to respond to a particular human by watching each other's sessions, the human who was selfish with one parrot was giving with the other; humans never altered choices when interacting with a given bird. The copycat, whose stance was essentially neutral, maintained her role with both birds. These parrots had been trained by humans for over a decade (e.g. Pepperberg 1999; Pepperberg and Shive 2001; Pepperberg and Wilcox 2000; Pepperberg and Wilkes 2004), and other Grey parrots in similar situations have, as noted above, learned to adapt their responses to overt human behavioural actions (Giret et al. 2009; Péron et al. 2010, 2011a, b), thus we expected them to associate a stance with a particular human and react appropriately, much as do primates (Intentional/Accidental: Call and Tomasello 1998; Unable/Unwilling: Call et al. 2004; Phillips et al. 2009).

Parrots were thus tested as to their choice among four differentially valued tokens, and whether they would react to the behaviour of their various partners. We predicted that, if parrots understood the reward system, they would, in the first study, develop a preference for the sharing token and thereby maximize their overall pay-off. Specifically, the *immediate* reward would be the same if they shared or were selfish but, if both attended to each other's choices and consistently chose to share (at *no* cost to themselves, a limited form of prosociality), they could maximize their total reward. In the second study, in contrast, we predicted they would either replicate the choice of the experimenter, as their standard training involves learning from human modelling sessions (Pepperberg 1999), or attempt to act as demonstrators themselves by choosing the sharing cup to maximize reward.

Individual personalities of our two birds clearly might affect our results; however, our limited subject pool confers certain advantages. Because several studies show reciprocity is not contingent on short-term, tit-for-tat rules but rather long-term interactions (review in Massen et al. 2011), detailed knowledge of our two birds' interactions with each other for over 9 years and with humans for over a decade, and their stable dominance relationship, provides some bases for our findings. Unfortunately, few captive flocks of

Grey parrots are available for study, and those may be comprised of 'rescue' birds, sometimes with serious social problems (e.g. prior abuse, previously living without social interaction of any sort, etc.) that could hinder studies of prosociality and reciprocity, both with other birds and humans. Our results can be seen as a first step in examining sharing and reciprocity in Grey parrots and should provide impetus for further examination of this behaviour, a topic of considerable interest given the similarities of the psittacine lifestyle to that of primates in nature.

General methods

Subjects and housing

Two hand-reared male Grey parrots were tested during July–December 2009: 14-yr-old Griffin and 11-yr-old Arthur. Griffin was dominant to Arthur. Both birds have been the subject of continuing studies on comparative cognition and interspecies communication (e.g. Pepperberg 1999, 2004; Pepperberg et al. 1998, 1999, 2000; Pepperberg and Shive 2001; Pepperberg and Wilcox 2000; Pepperberg and Wilkes 2004). Details of housing conditions are in Pepperberg and Wilkes (2004). Outside of testing, birds lived separately in or on large cages out of reach of one another, in the same room, but sometimes display aggressively. Birds were never food or water deprived at any time during experiments.

Materials and general method

Four same-sized plastic cups of differing colours (*First Years Stack N Count Cups*TM) were placed on a felt-covered tray equidistant from a parrot's beak (Fig. 1), and rewards consistent with each cup colour were put under each cup without birds observing the placement (see below). The set-up ensured that human cuing via gaze of a particular choice of cup would not be an issue: Cups were closely spaced (<5 cm) on a tray and the human head was about 30 cm away from the tray, a situation in which parrots have not previously been shown to react to human gaze direction (Pepperberg 1990, 1999), unlike that of Giret et al. (2009) in which Grey parrots did respond to human gaze when objects were 1.6 m apart and the human face was deliberately turned in the direction of one of the objects.

The same materials were used for all experimental trials. The specific cups were novel, but both birds had interacted with similar cups previously (e.g. object permanence, Pepperberg et al. 1997) and thus showed no neophobia or other aversive behaviour towards these items. Because Griffin and another Grey parrot, Alex, had already shown in object permanence tasks that they would, in the absence

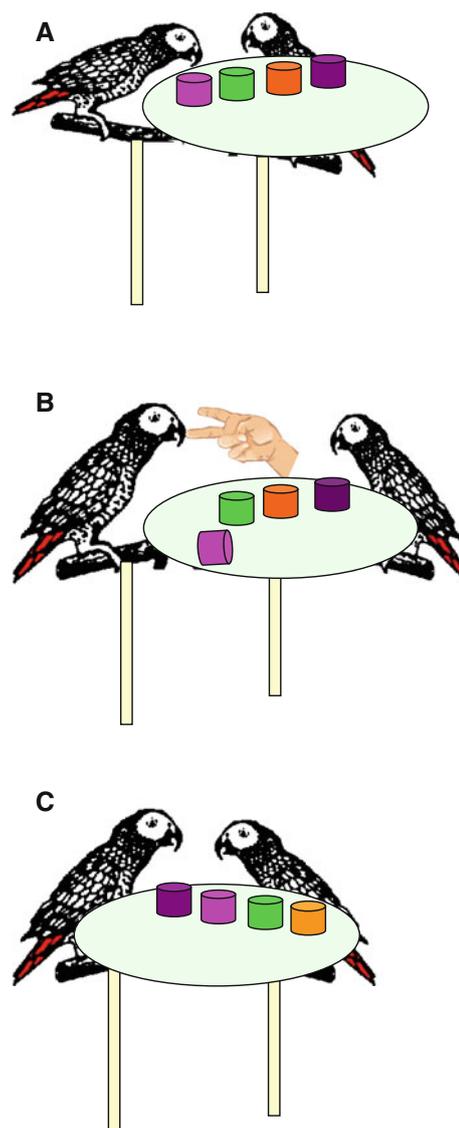


Fig. 1 Experiment 1. Position of birds and tray during trials; during trials, cups are arranged so as to be equidistant from the beak of the bird that makes the choice. In **a** Griffin chooses as Arthur watches; in **b** human gives Griffin the reward (selfish choice); in **c** Arthur gets ready to choose as Griffin watches

of another bird, appropriately choose the cup among several that contained hidden rewards (Pepperberg et al. 1997), we did not test to see whether competition was required for birds to track rewards. We first tested to ensure that birds had no colour biases, then attributed arbitrary values to each cup colour. The tray was also familiar, having been used with both birds for several years to present various study items (e.g. Pepperberg et al. 1997; Pepperberg and Wilkes 2004). Rewards—pieces of cashews, almonds, occasionally small candies—were special treats not available except in experimental sessions.

No familiarization phase was needed; birds were used to interacting with the cups in this manner. If a bird hesitated,

he was told “Go pick up cup.” For each trial, we recorded the choice of the birds and, in Experiment 1, any additional behaviour of each individual (vocal production, displacement, etc.). In Experiment 2, additional physical but not vocal behaviour was noted.

Experiment 1

Protocol

Birds perched close enough to one another to observe each other's choice, but outside of beak range to avoid possible aggression. Out of view of the birds, an experimenter placed the cups on a tray, with the appropriate rewards hidden underneath: The green cup held 2 treats, pink and orange cups held 1 each, the violet cup held none. If a bird chose (a) green cup—sharing, he and his partner each got treats; (b) pink cup—selfish, only he got a treat, (c) orange cup—giving, only his partner got a treat, and (d) violet cup—null (spiteful/opt out), no one got treats. Cups were equidistant from the beak of the bird making the choice, and order was counterbalanced such that one bird started one particular session of trials (the leader) and, in most instances, order was reversed in the next session (i.e. that bird became the follower). Birds worked as a dyad, such that each two-choice trial consisted of the following pattern: The tray was presented to the lead bird; after he chose a cup (either by picking it up or pecking it), the experimenter intervened and distributed the reward according to the cup's value. While birds ate the reward, the tray was re-baited (out of sight of the birds), then immediately presented to the follower for his choice and subsequent reward disbursement by the experimenter. Inter-choice and inter-trial intervals (i.e. time needed to re-bait and re-present the tray, approximately 12–15 s) were kept as consistent as possible; the idea was to model what might be a feeding session in the wild, where the first bird to arrive at, for example, a fruiting tree, might have some advantage, but then feeding by the flock is more or less simultaneous, excepting various affiliative and aggressive flock interactions (May 2004).

We also examined the relevance of cup placement on the tray, by changing their order randomly, to determine whether birds would indeed respond to colour/value versus spatial array; that is, we needed to test whether birds might have spatial preferences that could affect their choices separate from the reward level of the cup. In Experiment 1, we used random changes so birds could not deduce or anticipate systematic changes in presentations. We could then compare their behaviour with other sessions in which cup order had not been altered.

		Individual 1			
		sharing (green)	selfish (pink)	giving (orange)	null (violet)
Individual 2	sharing (green)	2 / 2	2 / 1	1 / 2	1 / 1
	selfish (pink)	1 / 2	1 / 1	0 / 2	0 / 1
	giving (orange)	2 / 1	2 / 0	1 / 1	1 / 0
	null (violet)	1 / 1	1 / 0	0 / 1	0 / 0

Fig. 2 Experiments 1 and 2. Payoff matrix, showing the number of treats involved in each possible outcome for a *two-choice* trial, depending on a bird's choice and its partner's choice. For example: If both individuals chose to share on a given trial, each bird would get two rewards (*upper left corner*); if individual 1 acts selfishly but individual 2 shares, individual 1 gets two rewards and individual 2 gets only one (*top row, cell second from left*) as their total for the trial

Birds engaged in 50 sessions of 20 choices—10 for each bird—having two sessions most weekdays and some weekend days for approximately 1 month. Of these 50 sessions, Griffin led in 24 and Arthur led in 26 (one session was inverted by mistake). The large number of sessions enabled us to distinguish short-term tit-for-tat versus longer-term interactions. Experimenters did not perform more than two sessions on any given day; occasionally a single session occurred because of human scheduling.

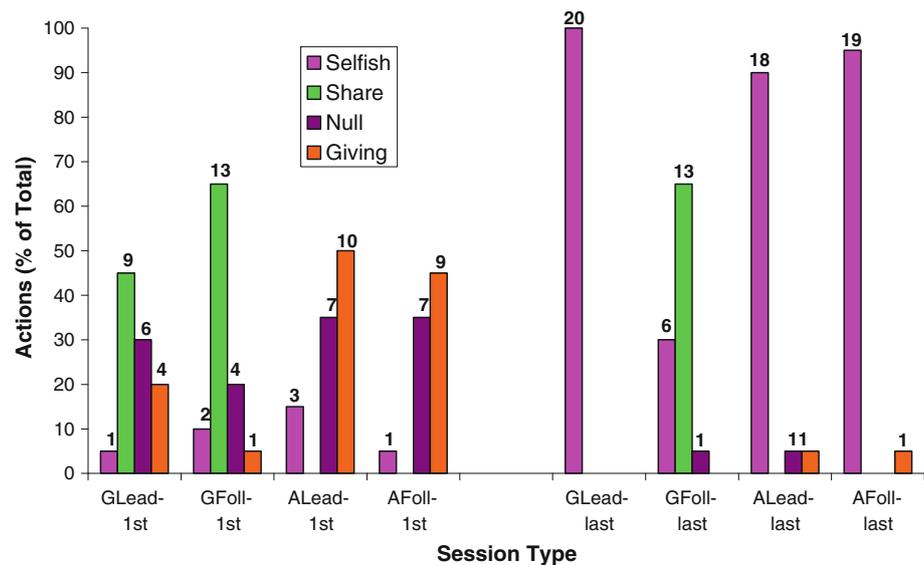
Given the value of each cup and that individuals acted successively, a payoff matrix could be constructed, based on the birds' paired choices (see Fig. 2). If the birds did attend—or learned to attend—to each other's actions and reciprocated by choosing the green (sharing) cup, they could maximize the payoff, because each bird would receive a reward on each turn. Whether they would act in this manner was the subject of this Experiment.

Demonstrations

To assist birds in understanding the value of each choice of cup colour, rather than their having to learn entirely via trial-and-error, they received brief demonstrations prior to testing, using our standard Model/Rival technique (Pepperberg 1981, 1999; Pepperberg and Wilkes 2004). In each demonstration, two humans sequentially showed birds the consequences of choosing a particular cup; a third person distributed rewards accordingly. Birds saw 12 choices alternating among the cup colours (i.e. 3/colour). These demonstrations helped birds acquire an understanding of the basic concept of the task, but birds were not trained to perform in any particular manner, as all consequences were demonstrated equally.

Fig. 3 Experiment 1.

Comparison of parrots' initial and final behaviour (20 trials/bird) depending on whether they were the first or second bird to choose a cup within a session



Results

Cup choices

Both birds immediately engaged in choosing various cups. To evaluate choices, we used Chi-square tests. The first, for randomness, determined whether birds simply chose without regard to consequences. Results ($\chi^2 = 10.3$, $P = 0.016$, $df = 3$) showed that, overall, birds were not responding at random over all 50 sessions. We also determined whether results were the same whether Griffin or Arthur led a session—that is, to see whether who led and who followed affected the results. Notably, here a significant difference existed ($\chi^2 = 13.7$, $P < 0.005$, $df = 3$). Finally, Chi-square tests showed that nonrandom choice occurred for each bird in each condition (Griffin, leader: $\chi^2 = 64.5$, $P < 0.01$, $df = 3$; Griffin, follower: $\chi^2 = 42.2$, $P < 0.01$, $df = 3$; Arthur, leader: $\chi^2 = 45.7$, $P < 0.01$, $df = 3$; Arthur, follower: $\chi^2 = 11.6$, $P = 0.01$, $df = 3$).

To examine effects of who led/followed and evolution of choices over time, we divided sessions with respect to which bird led and which followed, and also midway (i.e. into first and last halves with respect to session number), comparing results across each half. The full data set is shown in Figure S1. Birds learned that different cup colours represented different values and adjusted their behaviour consistent with those values: They tended to stop choosing violet (no reward) and orange (rewarding the other bird) and tended to increase choices of pink (selfish) or retain choices of green (sharing). Chi-square tests confirmed that birds altered behaviour patterns over time. For each bird in each role, differences between first and second halves of the study were significant. For Griffin as leader: $\chi^2 = 31.9$, $P < 0.01$, $df = 3$; as follower: $\chi^2 = 31.0$, $P < 0.01$, $df = 3$; for Arthur as leader: $\chi^2 = 13.4$, $P < 0.01$, $df = 3$; as follower: $\chi^2 = 15.3$, $P < 0.01$, $df = 3$.

Examining birds' choices in their first and last 40 trials (20 per bird; Fig. 3) highlights their behaviour: they behaved somewhat differently depending on who led or followed. When leading, Griffin shifted all his choices to selfish at the end (pink; statistically significantly, $\chi^2 = 30.1$, $P < 0.01$, $df = 3$). When Griffin was the follower, although he decreased his choices of giving (orange) and null (violet), and slightly increased choice of selfish (pink), he continued sharing at the same rate, and differences between these starting and ending behaviour patterns were not significant ($\chi^2 = 3.8$, $P = \text{ns}$, $df = 3$). Arthur's choices in the first sessions, both as leader and follower, were significantly different from chance (respectively, $\chi^2 = 11.6$, $P = 0.01$, $df = 3$; $\chi^2 = 9.2$, $P = 0.03$, $df = 3$). He started with a slight giving tendency as both leader and follower, then became statistically significantly more selfish both as leader and follower (respectively, $\chi^2 = 21$, $P < 0.01$, $df = 3$; $\chi^2 = 21.3$, $P < 0.01$, $df = 1$). Given the high variability of the data, additional statistical analyses are unlikely to provide additional information. A discussion of observable trends in the raw data, however, can be found in Electronic Supplemental Material, Figure S1 Comments. To avoid performing Chi-square with zeros, in all such cases, we added 0.5 to all values in the calculation (Field 2009). Having a large number of entries of zero and more than 20 % of less than 5 precluded log-linear analyses of the full data set.

We also examined relevance of cup placement on the tray; changes are marked by arrows in Figure S1. Birds' behaviour patterns sometimes changed at the point of a shift; however, even more significant behavioural differences occurred between sessions in which no changes in cup order had been made. Chi-square tests showed that behaviour before and after cup order switches was not significantly different for Griffin as

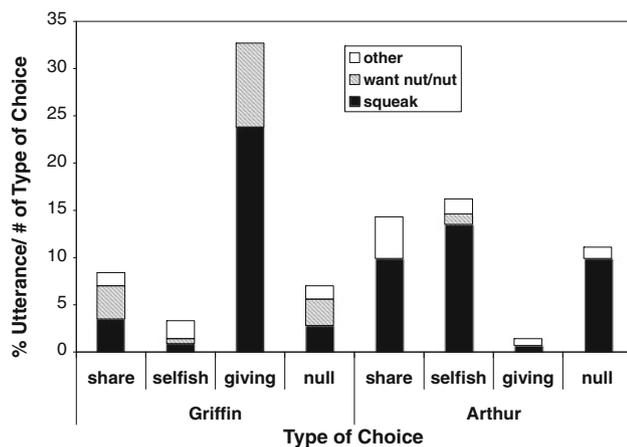


Fig. 4 Experiment 1. Griffin's vocalizations graphed as percentages relative to numbers of choices each bird made

leader (e.g. at session 9, $\chi^2 = 2.1$, $P = \text{ns}$, $df = 3$). As a follower, Griffin's behaviour altered less when cup order changed (e.g. at session 8, $\chi^2 = 9.9$, $P = 0.02$, $df = 3$), than when no cup switch was made (e.g. between sessions 12 and 13, $\chi^2 = 14.4$, $P < 0.01$, $df = 3$). Similar results were found for Arthur. Thus cup order may have had some influence right at the point of a switch, but less so than experiencing alterations in each others' actions. Figure S1, by presenting variability in data across sessions, rather than in just initial and final sessions (Fig. 3) as in most studies, suggests that birds were likely responding to each others' cup choices.

Although Arthur was placed so as to see Griffin's behaviour, he sometimes did not seem to be observing Griffin's choices. He appeared merely to be waiting his turn to choose a reward.

Vocal behaviour

During sessions, Griffin emitted three main vocalizations: calls that could be interpreted as "frustration squeaks" (see below), requests of "want nut", or statements of "nut". Arthur remained silent throughout. We recorded number and type of utterances according to the cup chosen (see Fig. 4).

Vocalizations were, overall, very few (ca. 1-2/session, where each session involved 20 choices). Griffin significantly produced more calls that had previously been associated with frustration (e.g. given when students ignore his requests, or when he fails in an endeavour) when he received none than when he received half the visible reward ($\chi^2 = 21.062$, $P < 0.001$, $df = 1$). Looking at the percentage per choice shows he emitted the three main utterances 33 % of the time when he chose orange (22 utterances, of which 16 were squeaks, during 67 choices) and 16 % of the time when Arthur chose pink (27 in 185 choices, 25 squeaks) but no more than ~7 % of the time when he chose green (10 in 143 choices, 5

squeaks) or ~10 % of the time Arthur chose green (9 in 91 choices, all squeaks). He rarely vocalized when he chose pink (3 of 214, 2 squeaks) or Arthur chose orange (1 of 137, 1 squeak). He also said "want nut" or "nut" more often when he received nothing versus all the reward ($\chi^2 = 6.4$, $P = 0.011$, $df = 1$), and less often when he received half, but only ~15 such requests occurred overall in ~1,000 choices, and because half these vocalizations were "nut", they could equally have been a comment rather than a request.

Discussion

Two main findings emerge: First, birds recognized that tokens had different values and altered their behaviour to some degree accordingly. Second, like chimpanzees in some studies (e.g. Brosnan et al. 2009; Melis et al. 2008; Silk et al. 2005), birds were not overtly eager to share or reciprocate; that is, if we combine results for their actions as both leaders and followers, they did not cooperatively act so as to maximize rewards. However, whether they shared with their partner at no cost to themselves seemed, at least for our subjects, to depend upon their dominance status and upon who led and who followed. Griffin has always been dominant to Arthur, and Figs. 3 and S1 show that when Griffin led, he became selfish, but when placed in the position of follower, he acted in a more sharing manner. Notably, both birds generally decreased their choices of giving and null cups: those choices did not result in any immediate personal reward and any overt giving was not reciprocated. Results suggest that they either did not understand the advantage of reciprocally choosing green (sharing) in order to maximize payoff, or their dominant-subordinate relationship interfered with their interactions. Possibly seeing half the reward under the green cup—which, at double the amount under the selfish (pink) and giving (orange) cups, may have seemed like a bonus—go instead to the partner might have created a negative association for the bird making the choice. Such might have been the case for Arthur. However, Griffin rarely produced calls indicating frustration in such instances and did chose green with increasing frequency as trials progressed when he was the follower. Had choosing green created a negative association for him, such would not have been the case.

The birds were not automatons; session-to-session variation frequently occurred (Figure S1). Possibly, birds responded not only with respect to their social/asocial tendencies per se, but also to differing daily conditions we chose not to control (e.g. how much/what types of other food they might already have had, how long since they had eaten, how much interaction they had had prior to a session, how many training/testing sessions had been held on totally different topics that day). Such conditions might

stand in for variability of life in the wild that would affect their natural behaviour on this task. Conceivably, Griffin acted in a somewhat Machiavellian manner, like Massen et al.'s (2010) macaques. As leader, he responded selfishly. However, when uncharacteristically forced into a following position, he may have, in the sense of Zahavi (2004), tried to advertise his fitness via sharing, and re-establish his dominance. He was more than twice as likely to choose green as pink when a follower in the last 20 trials (Fig. 3). Massen et al. (2011), for example, argue that prosocial behaviour may signal status particularly for individuals living in fission–fusion societies, where it can be “used to signal a positive attitude in the presence of unfamiliar individuals or after reencountering known individuals...” Also, Griffin (although quite rarely) requested nuts or commented when nuts went to Arthur; one might argue such utterances could be interpreted as requests for assistance. If so, Arthur, unlike apes in some studies (e.g. Melis et al. 2011), did not respond.

Arthur, the subordinate, behaved differently. Initially, he tended towards donating treats to Griffin or a choice (null) benefitting neither (possibly conflicted between not wanting to donate but being afraid to take the treat in Griffin's presence). He thus initially acted like apes in some studies (e.g. Yamamoto et al. 2009). Because, as in a recent chimpanzee study (Horner et al. 2011), humans actually disbursed the treats, he may have *learned* that he could, in this unique situation in the laboratory, be selfish without fear of reprisal from Griffin; Arthur's behaviour—a shift to selfish as both leader and follower—suggests such might be the case.

Interestingly, one reason for alternating birds' positions as leader and follower had been to see whether the effect of dominance on behaviour would hold up in our laboratory if the dominant bird had to follow and the subordinate bird was given the chance to lead, that is, if we made at least some attempt to change the hierarchical nature of life in the laboratory. Data (Fig. 3, S1) demonstrate that little change occurred initially; only over the course of the experiment did birds' behaviour patterns evolve.

Clearly, our data are preliminary: We tested only two birds, and our observations about dominance/subordination may be relevant only in our laboratory or only as part of an interactive equation. Repetition, with a flock of Greys that have socially interacted since hatching, that live in a monitored dominance hierarchy, and for whom detailed knowledge of all partnerships exists so tests can examine interconnected effects of age, sex, dominance, and social partnerships (e.g. Massen et al. 2011) would be necessary before species-wide conclusions could be formed. However, our paradigm suggests a simple, effective way to examine sharing and reciprocity in psittacids and likely other avian subjects.

Experiment 2

Because birds' responses in Experiment 1 could have been influenced by their (possible dominance) relationship with each other, we subsequently tested their behaviour in a situation that should have avoided that issue; that is, with human partners. We specifically investigated how and if the birds' behaviour (sharing or selfish) might be shaped by partners acting consistently in that manner. Also, we tested whether birds would come to understand the behaviour of a “copycat” human, who mirrored their actions, or whether such a partner, who changed behaviour from trial-to-trial, would prevent the avian chooser from recognizing or understanding the underlying pattern of mirroring.

Protocol

Birds were now tested individually in sessions with three different humans. One was selfish, always choosing pink; a second was giving, always choosing orange; a third mirrored whatever the bird did (“copycat”). The giving person for Arthur was selfish for Griffin and vice versa. Humans chose first for giving and selfish trials, to see how birds might respond to being the follower. Birds chose first on copycat trials, to see how human responses might affect the birds' behaviour. Different sessions were randomly interspersed, depending only on which trainer worked on a given day. For both birds, order of cup colours was changed within each session (every 5 trials) to examine their overall patterns with respect to order and to perform statistical tests. The remainder of the protocol was identical to that of Experiment 1. Birds were already familiar with cup values; no demonstrations were needed.

In all but a few instances, birds had ten sessions of ten trials each in each condition. Given the need to maintain consistency of human partners and schedules of these partners over time, however, Griffin had only nine sessions in the giving condition and Arthur had only nine selfish sessions. We tried to give birds at least one session/day and no more than two sessions/day, but because of the number of humans involved, adherence to this schedule was difficult. Thus, on occasion (student vacation time, exam period), Arthur did not get sessions for 3 weeks or Griffin had four sessions on 1 day. Such aberrations may have affected the results (see below).

Results

Chi-square tests showed that birds did not have any spatial preference (e.g. for inner versus outer cups; Fig. 1: for Griffin, $\chi^2 = 2.49$, $P = 0.11$; for Arthur, $\chi^2 = 2.67$, $P = 0.10$). Thus their choices reflected an understanding of the value of cup colours and not preferences for spacing or position of the cups.

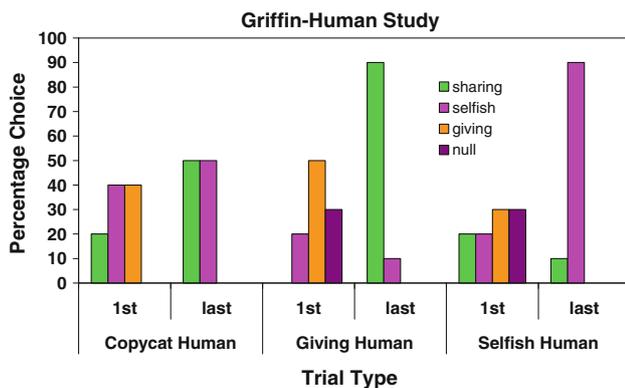


Fig. 5 Experiment 2. Comparisons of Griffin's initial and final sessions for the three different human interactions, based on percentages of his total responses

Both birds reacted in ways at least somewhat consistent with actions of their human partners and with their experience in Experiment 1. Both birds, in all situations, either remembered to avoid the null cup on the first session or quickly learned to avoid it; again, they also tended not to donate rewards to their human partner—that is, they avoided orange—even if the partner had chosen orange. Their responses with respect to selfishness and sharing differed somewhat for each bird and each situation. An overall summation of their choices, however, tells little about their behaviour, as it is the change in behaviour relative to the different human actions that is the issue. We plot first and last sessions in each condition (10 trials each) to emphasize the birds' behavioural change over time; additional graphs provide choices for each session for each bird for each condition (Figs. S2, S3). The number of data points for 10 trials was too low for Chi-square calculations comparing first versus last sessions, and the data too erratic overall for statistical analyses; we discuss only trends that appear over time.

Griffin

Griffin interacted in ways somewhat consistent with that of his human partners (Figs. 5, S2). Some trends are apparent from the early and final sessions (Fig. 5) and the overall data (Fig. S2). When paired with a giving human (who always chose orange), Griffin's behaviour shifted in a generally straightforward way, towards sharing. He was clearly not mimicking the human or responding in a form of stimulus enhancement, because he shifted towards the sharing (green) cup, not the orange. He also decreased his selfish (pink), giving (orange), and null (violet) choices. Similarly, when paired with an always selfish human, he shifted towards selfish behaviour and away from giving, null, and sharing choices. His increase in selfishness over

time and decrease in giving are apparent, particularly in the last few sessions. Griffin's behaviour with the copycat human demonstrates few apparent trends and would seem not to show any understanding that the human was indeed following his behaviour and that a clear change towards sharing would increase the total number of treats he might receive. However, he appears to increase sharing over time, whereas selfishness remains relatively steady and choice of the orange cup decreases.

Arthur

Arthur did not behave as consistently towards humans as did Griffin (Figs. 6, S3). For reasons described below, Fig. 6 uses session 8, not session 10, as 'last' for interactions with the giving human. Figure 6 shows that Arthur tended towards sharing with the giving human and towards selfishness with the selfish human, and that he, like Griffin, seemed confused by the copycat situation. With the "copycat", interestingly, he often stopped giving rewards, often 'opting out' by choosing the null cup; his giving (choice of orange) trended downward.

Inspection of individual sessions (Fig. S3) shows at least one interesting trend. Separation of the last two sessions, held after a three-week break—over twice as long as any other break in the entire experiment—appears important for analysis: With the giving human, he was tending towards an increase in sharing and a decrease in selfishness before the break, with a clear reversal afterwards.

Discussion

When intraspecies interactions were not relevant and humans acted consistently, at least one Grey parrot appeared to develop some understanding of sharing and reciprocity. Griffin's actions with a consistently giving trainer suggested he might have inferred that choosing green (sharing) would ensure he received a maximum number of rewards and that he could reward his giving partner at no real cost to himself. He could have consistently been selfish and garnered the same reward level, but did not. He was definitely not copying the human's behaviour overall, because the human consistently gave him the immediate reward—chose *orange*. Arthur, in contrast, did not seem willing to give that partner much reward, even at no cost to himself, although he did trend towards sharing with the giving trainer before the three-week break. Possibly, Arthur, who, unlike Griffin, often reacts to an absence by a student with whom he has previously had positive interactions (e.g. allows to scratch his head) by seriously biting or ignoring this human upon his/her return, might have used a selfish choice to indicate his displeasure at being 'abandoned' for the 3-week hiatus.

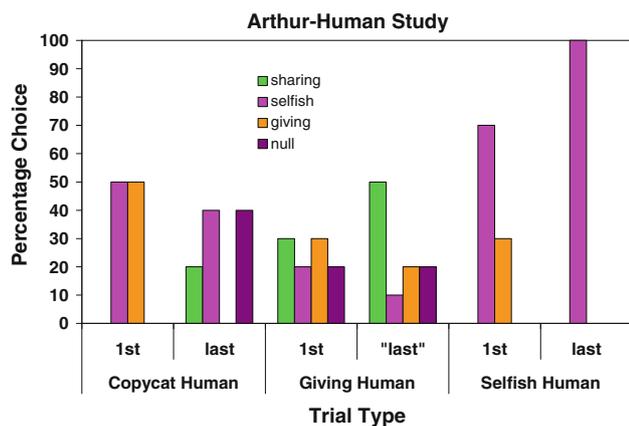


Fig. 6 Experiment 2. Comparisons of Arthur's initial and not-quite final sessions (because of the 3-week testing break) for the three different human interactions, based on percentages of his total responses

Birds also differed with respect to the selfish human partner. Griffin became considerably more selfish, suggesting that he again altered his responses based on those of his partner. Arthur was already selfish in the first session with the selfish partner, possibly immediately reacting to the observed selfishness, but his subsequent behaviour was mostly random until the final session. Though no long breaks occurred in Arthur's interactions with the selfish trainer, unlike the break with the generous one, conceivably the selfish behaviour transferred between those final sessions, as they were held during the same time period.

The copycat situation, where the human partner acted neither consistently generously nor selfishly, seemed to confuse the birds. Griffin did not respond in a clearly consistent manner. Had he consistently chosen green, we would have had evidence that he inferred the underlying principle: by sharing at no cost to himself, his partner would reciprocate and he could maximize rewards. He did, however, trend in the appropriate direction; thus, possibly, he had begun to test out an inference about the reciprocity of the situation. Had sessions extended for a longer period (as in Experiment 1), maybe he would have responded appropriately. Arthur at first trended towards sharing, but, in contrast, halfway through changed his behaviour; his tendency towards an increase in the null response (violet) might suggest a lack of willingness to continue to participate in the interactions.

Again, as in Experiment 1, we summarize changes over time in Figs. 5 and 6, and present full data sets in Figures S2 and S3. A clearer case for sharing and reciprocity could be made with the summary data; however, Figures S2 and S3 show that despite some trends, session-to-session variability existed, again probably as a result of the other laboratory conditions noted above.

Though Griffin and Arthur had both been previously extensively trained by humans via the Model/Rival method

(Pepperberg 1981), and thus expect humans to demonstrate behaviour patterns they are to learn, such training did not likely affect their overall behaviour here. Training background might have affected their initial choices—for example, with the giving human who always picked orange—but clearly had no effect by the final session. Importantly, only the copycat human ever picked green (sharing), but Griffin clearly switched to green with the giving human, suggesting that he, at least, began to understand the issues involved.

Note, too, that although several weeks elapsed between Experiments 1 and 2, birds likely remembered the values of the cups, as can be seen, for example, by their low choice of null (violet) on several initial sessions. Thus any learning curves in Experiment 2 were likely to be solely related to their reactions to the different social systems.

General discussion

Overall, we found three interesting results. First, both birds were sensitive to token values (i.e. cup colour). Second, the relationship between the birds may have affected their interactions, but in somewhat unexpected ways. Third, when working with humans, Griffin's responses suggested some possible understanding of reciprocity and sharing, whereas Arthur's behaviour was more variable.

Both parrots were sensitive to the value of their choices and, to some extent, altered their behaviour accordingly. When working together, both birds learned to avoid cups (violet, orange) representing, and resulting in, lack of personal reward. Arthur, in particular, learned about aspects of the task specifically related to reward disbursement: He—our subordinate—initially either chose orange (giving) or null as both leader and follower (possibly waffling between acceding to our dominant and avoiding any nut disbursement), but became more selfish over time in both instances. Possibly he began to realize that, as humans disbursed rewards, Griffin could not punish his selfishness.

Parrots were also somewhat sensitive to reward distributions (i.e. consequences of cup colour) under various conditions. In Experiment 1, possibly the relationship between the two birds and whether they acted as follower or leader affected the extent to which they demonstrated sharing and reciprocity. In Experiment 2, Griffin appeared sensitive to the actions of his human partners, whereas Arthur demonstrated less consistency, although some responses may have been a consequence of session scheduling and the extended absence of one human partner.

We have studied only one pair of birds and clearly cannot draw widespread conclusions about dominance effects, but our data on dominance/subordination can be used for comparisons with subsequent studies. In Experiment 1, our

subordinate Arthur, like Massen et al.'s (2010) long-tailed macaques, seemed to learn he could be selfish without immediate consequences—that is, without fear of physical reprisal, whether he led or followed. Specifically, he began Experiment 1, both as leader and follower, by donating roughly half the rewards to Griffin, but ended by being almost exclusively selfish. Such behaviour suggests that Arthur learned he could gain an unusual advantage over our dominant bird. Even when working with humans (Experiment 2), Arthur showed little regard for the actions of the copycat partner. His response to the giving partner trended towards sharing before a three-week break in sessions, but became selfish afterwards. Although the point of using humans here was to avoid dominance/subordination issues, conceivably Arthur transferred his subordinate status with respect to Griffin to interactions with his human partners, given that humans in general are his source of food, drink, and social interaction in our laboratory. Interestingly, as noted above, he responded to the long absence of the giving partner by changing his behaviour towards her.

In Experiment 1, Griffin, as the dominant leader, possibly began by acting as though he could “afford” (in the sense of Zahavi 2004) to be generous at no cost to himself, but became selfish when his actions were not reciprocated. In contrast, however, when forced into the unusual position of follower, he did not alter the level of his sharing. As suggested by Massen et al. (2010), prosociality (or in our case, sharing) in a dominant might be a strategy to maintain—or here—reaffirm dominance (note de Waal 1989; Moore 1984; Zahavi 2004). Griffin's behaviour in Experiment 2 was consistent with the possibility that he did not see himself as dominant with respect to the humans in the laboratory: He became more willing to share with the giving human, selfish with the selfish human, and might have been tending towards sharing and reciprocity with the copycat human. Despite changes over time that suggest that Griffin, at least, began to behaviourally adjust to his partners' actions, we cannot claim that he was intentionally acting in a “tit-for-tat” manner.

During copycat sessions, neither bird seemed to realize that the human was indeed mirroring his behaviour, although Griffin may have understood the situation towards the end of the experiment. Conceivably, birds simply did not connect their behaviour with that of the human and instead may have interpreted the human as behaving erratically, in contrast to the other humans who demonstrated a specific agenda during the same time period. We suggest that copycat trials subsequently be performed as a separate experiment, without being contrasted with trials in which humans acted consistently, to determine whether results might have differed. Possibly, the birds needed consistency on the part of their partners to understand the interactions—or maybe *short-term* tit-for-tat is not as

important as developing long-term interactions for long-lived individuals.

Overall, birds were sensitive to context. Our mass trial procedure, the long break between sessions for Arthur in Experiment 2 (described above), and the occasional large number of sessions on 1 day, may all have affected both the parrots' willingness to work and their responses. For example, in a third session in 1 day, Arthur's null choice (violet) five of 10 times (Fig. S3) might have been his way of expressing lack of interest in continuing to work rather than a response to the specific actions of the human. Massing of trials (i.e. 10/bird/session) was necessary, given that birds needed the opportunity to decode any given situation, but possibly caused boredom and satiety. Switching treats may have alleviated, but likely did not eliminate, these issues.

Another explanation for our birds' behavioural differences is that Arthur may not be as cognitively advanced as Griffin. However, other studies, particularly on string-pulling (e.g. Pepperberg 2004) and a current trap-tube study, show that Arthur is adept (possibly more so than Griffin) at solving various ‘insight’ tasks. Conceivably, however, Arthur's insight into physical situations might not transfer to social interactions.

Comparing Grey parrot understanding of reciprocity and sharing to that of other nonhuman species, particularly with respect to prosociality, is difficult. As noted in the introduction, nonhuman primate data also seem extremely dependent upon experimental context, and our design was only somewhat similar to that of Horner et al. (2011). In particular, our study was conducted simultaneously with several other ongoing studies, as is the tradition in our laboratory and as a means of more likely replicating conditions outside of a laboratory. Again, although we have tested only one pair, we suggest that our birds' behaviour patterns somewhat resemble those of monkeys having dominance hierarchies (e.g. macaques, Massen et al. 2010), and that subsequent studies with more birds must be conducted to test our supposition. Of interest might be comparative studies with cooperatively breeding corvids, such as Florida scrub jays (*Aphelocoma coerulescens*). In cooperatively breeding green wood hoopoes (*Phoeniculus purpureus*), the dominant pair increases allopreening of helpers (who provide much of the territorial defence) when the group enter zones of potential conflict with neighbouring groups and decreases allopreening when the focal group leaves such zones (Radford 2011). Such behavioural change comes at a cost—for example, less time for feeding—and suggests that dominant birds might be trading preening for support, a form of reciprocity.

In sum, some level of reciprocity and sharing appears not to be limited to the primate line. Likely the same evolutionary pressures that were exerted to develop advanced cognitive and communicative abilities in both

primates and certain avian species (e.g. Emery 2004; Pepperberg 1999) also were engaged in the development of reciprocity and sharing. The expression of such behaviour is, however, fragile in birds as well as primates, and very heavily dependent upon the various contexts in which it is examined (note Horner et al. 2011; Warneken et al. 2011).

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